For detailed instructions see Controller Product Manual 51-52-25-135 or Limit Product Manual 51-52-25-136.

Step 1. Record Instrument Model \& Serial
Note: Check inside label on chassis (remove from case)

Model number: $\qquad$

Serial number: $\qquad$

ETL25: Limit Control, listed for safety interlock, single relay output
ETC25: Universal Control with outputs for 4-20mA current or relay or 3-position step (floating), 2 alarms, and digital input

ETC25A: Advanced Program with 4-20mA current and 2 alarms, or relay output and 1 alarm; auxiliary output and 1 digital input or no aux-out and 2 digital inputs; second input; setpoint programming; and IR configuration port.

Step 2. Dimensions and mounting
Note: For NEMA 4 water protection, install the 4 screws and washers into the indentations at the corners of the front bezel.


## Step 3. Wiring

Fig. 3-1: ETL25 Limit Control


Fig. 3-2: ETC25 for 4-20mA current driven actuators


Fig. 3-3: ETC25 for High-Low or On-Off Control


Fig. 3-4: ETC25 for Three Position Step Control of power-driven actuators

90-264VAC


Alternate alarm load connection
Maximum Load 5A/120VAC or 2.5A/240VAC

Fig. 3-5: ETC25 for Three Position Step Control of contact-driven actuators


Fig. 3-6: ETC25A for 4-20mA current driven actuators includes Set-Point Programming, Remote Set-Point, and Heat-Cool capabilities.


Fig. 3-7: ETC25 and ETC25A for 0-10VDC output.


Ri is a resistor to be added to the input terminals of the device. $R z$ is the input impedance of the device. It must be greater than 500 ohms.
a) Set OUTALG - CRANGE to $0-20 \mathrm{~mA}$ to get 0 V at $0 \%$
b) Measure or look up the input impedance of the driven device
c) Calculate Ri resistor value from the formula: $\mathrm{Ri}=(500 \times \mathrm{Rz}) /(\mathrm{Rz}-500)$
d) Choose a $1 \%$ resistor equal to or the next greater standard value for the calculated resistance and power rating of at least $1 / 4 \mathrm{~W}$.

Fig. 3-8: ETC25 wiring to VeriFlame and a $4-20 \mathrm{~mA}$ actuator
This circuit provides:

- a burner start position that is increased above the minimum firing rate,
- an alarm 1 setpoint to force the actuator to the minimum firing rate, and
- an alarm 2 setpoint to shut off the burner.


1. In this example Alarm 1 is set for high deviation, $\mathrm{A} 1 \mathrm{~S} 1 \mathrm{TY}=\mathrm{DE}, \mathrm{A} 1 \mathrm{~S} 1 \mathrm{HL}=\mathrm{HIGH}$. When the temperature exceeds the setpoint by the value entered for A1S1VA, then the contact closes across the current output causing the actuator to move to the low fire position. It will be held at low fire until the difference between the temperature and setpoint drops below the A1S1VA setting.
2. In this example Alarm 2 is also set for high deviation, A2S1TY $=\mathrm{DE}, \mathrm{A} 2 \mathrm{~S} 1 \mathrm{HL}=\mathrm{HIGH}$, except the value entered for A2S1VA is set greater than for alarm 1. If the application temperature keeps rising with the actuator at low fire, then the alarm 2 contact will open. This causes the CR2 contact to remove power from the interlock input of the flame safeguard and shut down the burner. When the difference between the temperature and setpoint falls within the A2S1VA setting, then power is restored to the flame safeguard interlock input and the burner is lit.
3. Digital input 1 is used to force the output to a specific value for a burner starting position. It is useful for burners that require a higher firing rate to light reliably but can be turned down lower after lit. In the OPTION group, DIGIN1 is set to manual failsafe MNFS. The value for the starting position is entered in the CONTRL group under FAILSF as a percentage of output.

| Fig 3-9 Alarm Relay Contact States | Alarm Relay Wiring | Variable NOT in Alarm State |  | Variable in Alarm State |  |
| :---: | :---: | :---: | :---: | :---: | :---: |
|  |  | Relay Contact | Indicators | Relay Contact | Indicators |
| 下 | N.O. - 5-6 or 8-9 | Closed | Off | Open | On |
| 左 | N.C. - 4-5 or 7-8 | Open |  | Closed |  |

Step 4. General Configuration Procedure

| Step | Operation | Press | Result |
| :---: | :---: | :---: | :---: |
| 1 | Enter Set Up Mode | Setup | $\begin{aligned} & \text { Upper Display }=\text { SET } \\ & \text { Lower Display }=\text { TUNING (This is the first Set Up Group title) } \end{aligned}$ |
| 2 | Select any Set Up Group | Setup | Sequentially displays each Set Up Group Prompt, as listed below in the Configuration Record Sheet. You can also use the or keys to scan the Set Up groups in both directions. Stop at the group title that describes the group of parameters you want to configure. Then proceed to the next step. |
| 3 | Select a Function Parameter |  | Upper Display = the current value or selection for the first function prompt of the selected Set Up group. <br> Lower Display = the first Function prompt within that Set Up group. <br> Sequentially displays the other function prompts of the Set Up group you have selected. Stop at the function prompt that you want to change and then proceed to the next step. |
| 4 | Change the Value or Selection | A or | Increments or decrements the value or selection that appears for the selected function prompt. If you change the value or selection of a parameter while in Set Up mode then decide not to enter it, press [M-A Reset] once-the original value or selection is recalled. |
| 5 | Enter the Value or Selection | Function | Enters value or selection made into memory after another key is pressed. |
| 6 | Exit <br> Configuration | $\begin{aligned} & \text { Lower } \\ & \text { Display } \\ & \hline \end{aligned}$ | Exits configuration mode and returns controller to the same state it was in immediately preceding entry into the Set Up mode. It stores any changes you have made. <br> If you do not press any keys for 30 seconds, the controller times out and reverts to the mode and display used prior to entry into Set Up mode. |

Table 4-1: ETC25 Steps to configure a 4-20mA Output Control [Do not use for ETC25A]

| Step | Operation | Press | Result |
| :---: | :---: | :---: | :---: |
| 1 | Select ALGOR Group | Setup | Upper Display = SET ; press sequentially until Lower Display = ALGOR |
| 2 | Select CTRALG Function Parameter | Function | Upper Display = displays present value to be changed <br> Lower Display = CTRALG |
| 3 | Set to Proportional Control Mode | A or | Upper Display = PIDA (also PIDB or PDMR) <br> Lower Display = CTRALG |
| 4 | Select OUTALG Group | Setup | $\begin{aligned} & \text { Upper Display = SET } \\ & \text { Lower Display = OUTALG } \end{aligned}$ |
| 5 | Select OUTALG Function |  | Upper Display = displays present value to be changed Lower Display = OUTALG |
| 6 | Set to Relay type | Aor | $\begin{aligned} & \text { Upper Display }=\text { RLY } \\ & \text { Lower Display }=\text { OUTALG } \end{aligned}$ |
| 7 | Select OPTION Group | Setup | $\begin{aligned} & \text { Upper Display = SET } \\ & \text { Lower Display = OPTION } \end{aligned}$ |
| 8 | Select AUXOUT Function Parameter | Function | Upper Display = displays present value to be changed <br> Lower Display = AUXOUT |
| 9 | Set to OUT | A or | $\begin{aligned} & \text { Upper Display = OUT } \\ & \text { Lower Display = AUXOUT } \end{aligned}$ |
| 10 | Verify 0 percent | Function | $\begin{aligned} & \text { Upper Display }=0.0 \\ & \text { Lower Display }=0 \text { PCT } \end{aligned}$ |
| 11 | Verify 100 percent | Function | $\begin{aligned} & \text { Upper Display }=100.0 \\ & \text { Lower Display }=100 \mathrm{PCT} \end{aligned}$ |
| 12 | Verify current starts at 4mA | Function | $\begin{aligned} & \text { Upper Display }=4-20 \\ & \text { Lower Display }=\text { CRANGE } \end{aligned}$ |
| 13 | Exit Configuration | $\begin{gathered} \text { Lower } \\ \text { Display } \end{gathered}$ | Exits configuration mode and returns controller to the same state it was in immediately preceding entry into the Set Up mode. |

NOTE: Although the ETC25 controller is used for current output, the OUTALG is set to RLY to match the physical hardware installed for output 1 and output 2 terminals. Therefore the RLYTYP must also remain set at MECH. The RLYTYP parameter is only viewed when LOCK is set to NONE.

Table 4-2: ETC25 Steps to configure ON-OFF or HIGH-LOW Output Control [for ETC25A use OUT2 per Fig.3-6]

| Step | Operation | Press | Result |
| :---: | :--- | :--- | :--- |
| $\mathbf{1}$ | Select ALGOR Group | Setup | Upper Display = SET ; press sequentially until <br> Lower Display = ALGOR |
| $\mathbf{2}$ | Select CTRALG Function Parameter | Function | Upper Display = displays present value to be changed <br> Lower Display = CTRALG |
| $\mathbf{3}$ | Set to On-Off Control Mode | Upper Display = ONOF <br> Lower Display = CTRALG |  |
| $\mathbf{4}$ | Select OUTALG Group | Setup | Upper Display = SET <br> Lower Display = OUTALG |
| $\mathbf{5}$ | Select OUTALG Function | Function | Upper Display = displays present value to be changed <br> Lower Display = OUTALG |
| $\mathbf{6}$ | Set to Relay type | Upper Display = RLY <br> Lower Display = OUTALG |  |
| $\mathbf{7}$ | Exit Configuration | Lower <br> Eisplay configuration mode and returns controller to the same state it was <br> in immediately preceding entry into the Set Up mode. |  |

Note: The RLYTYP must remain set at MECH. The RLYTYP parameter is only viewed when LOCK is set to NONE.

Table 4-3: ETC25 Steps to configure Three-Position-Step Output Control

| Step | Operation | Press | Result |
| :---: | :---: | :---: | :---: |
| 1 | Select ALGOR Group | Setup | Upper Display = SET ; press sequentially until Lower Display = ALGOR |
| 2 | Select CTRALG Function Parameter | Function | ```Upper Display = displays present value to be changed Lower Display = CTRALG``` |
| 3 | Set to 3-Position Step Mode | A or ${ }^{\text {r }}$ | $\begin{aligned} & \text { Upper Display }=\text { TPSC } \\ & \text { Lower Display }=\text { CTRALG } \end{aligned}$ |
| 4 | Select OUTALG Group | Setup | $\begin{aligned} & \text { Upper Display = SET } \\ & \text { Lower Display = OUTALG } \end{aligned}$ |
| 5 | Verify OUTALG Function | Function | $\begin{aligned} & \text { Upper Display = TPSC } \\ & \text { Lower Display = OUTALG } \end{aligned}$ |
| 6 | Select Motor Stroke Time Function Parameter | Function | $\begin{aligned} & \text { Upper Display }=\text { displays present value to be changed } \\ & \text { Lower Display }=\text { MTR TI } \end{aligned}$ |
| 7 | Set Actuator Motor Travel Time Value in Seconds | $A \text { or }$ | $\begin{aligned} & \text { Upper Display }=\text { XX (enter time in seconds for } 0 \text { to } 100 \% \text { of stroke) } \\ & \text { Lower Display }=\text { MTR TI } \end{aligned}$ |
| 8 | Exit Configuration | $\begin{gathered} \text { Lower } \\ \text { Display } \end{gathered}$ | Exits configuration mode and returns controller to the same state it was in immediately preceding entry into the Set Up mode. |

NOTE: TPSC on the ETC25A uses the Alarm 1 (Output 3 terminals) and Alarm 2 (Output 4 terminals). The RLYTYP must remain set at MECH. The RLYTYP parameter is only viewed when LOCK is set to NONE.

## Step 5. Configuration Record Sheet

Table 5-1: ETL25 Limit Control - Enter the value or selection for each prompt on this sheet so you will have a record of your controller settings.

| Group Prompt | Function Prompt | Value or Selection | Factory Setting | Group Prompt | Function Prompt | Value or Selection | Factory Setting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| LOCK | SECUR LOCK |  | $\begin{aligned} & \text { DIS } \\ & \text { CAL } \end{aligned}$ | COM <br> Not Installed | ComADR <br> ComSTA <br> IRENAB <br> SDENAB <br> SHDTIM <br> BAUD <br> TX DLY <br> WS FLT <br> UNITS <br> LOOPBK |  | 3 <br> DIS <br> ENAB <br> ENAB |
| LIMIT | LOW-HIGH POWRUP SP MAX SP MIN DISPLY |  | HIGH <br> NORM <br> 2400 <br> 0 <br> PROC |  |  |  | $\begin{aligned} & 0 \\ & 19200 \\ & 1 \\ & \mathrm{FP} \\ & \mathrm{PCT} \\ & \mathrm{DIS} \end{aligned}$ |
| INPUT1 | IN1TYP <br> XMITR1 <br> IN1 HI <br> IN1 LO <br> BIAS 1 <br> FILTR1 BRNOUT EMIS |  | KH <br> LIN <br> 2400 <br> 0 <br> 0.0 <br> 1.0 <br> UP <br> 1.0 | ALARMS <br> Relays Not Installed, Use for Visual Alarm Indication Only | A1S1TY <br> A1S1VA <br> A1S1HL <br> A1S2TY <br> A1S2VA <br> A1S2HL <br> A2S1TY <br> A2S1VA <br> A2S1HL <br> A2S2TY <br> A2S2VA <br> A2S2HL <br> ALHYST <br> ALARM1 <br> BLOCK <br> DIAGAL | _ | NONE 90 HIGH NONE 10 HIGH NONE 95 |
| OPTIONS <br> Not Installed | AUXOUT 0 PCT 100 PCT CRANGE DIGIN1 |  | $\begin{aligned} & \text { DIS } \\ & 0 \\ & 100 \\ & 4-20 \\ & \text { DIS } \end{aligned}$ |  |  |  | HIGH NONE 5 <br> HIGH <br> 0.1 <br> NOL <br> DIS <br> DIS |
|  |  |  |  | DISPLY | $\begin{aligned} & \text { DECML } \\ & \text { UNITS } \\ & \text { FREQ } \end{aligned}$ | $\qquad$ | $\begin{aligned} & \text { NONE } \\ & \text { F } \\ & 60 \end{aligned}$ |

Note: To prevent accidental changes to the set point, adjust SP MAX and SP MIN in the LIMIT group to the desired set point value.

Table 5-2: ETC25 \& ETC25A Control - Enter the value or selection for each prompt on this sheet so you will have a record of your controller settings. Some prompts may not appear due to other prompt settings. Settings marked * are for the ETC25A.

| Group Prompt | Function Prompt | Value or Selection | Factory Setting | Group Prompt | Function Prompt | Value or Selection | Factory Setting |
| :---: | :---: | :---: | :---: | :---: | :---: | :---: | :---: |
| TUNING <br>  <br>  <br>  <br>  <br>  <br>  <br>  <br> SPRAMP | PB or GAIN <br> RATE T <br> I MIN or I RPM <br> MANRST <br> PB2 or GAIN 2 <br> RATE2T <br> I2 MIN or I2 RPM <br> CYCT1 or CT1X3 <br> CYC2T2 or CT2X3 <br> SECUR <br> LOCK <br> AUTOMA <br> RN HLD <br> SP SEL <br> SPRAMP <br> TI MIN <br> FINLSP |  | $\begin{array}{\|l} 10.00 \text { (PB) } \\ 0.00 \\ 1.20 \text { (I RPM) } \\ 0.0 \\ 5.00 \\ 0.20 \\ 1.30 \\ 10 \\ 10 \\ 0 \\ \text { CAL } \\ \text { ENAB } \\ \text { ENAB } \\ \text { ENAB } \\ \\ \hline \text { DIS } \\ 3 \\ 1000 \end{array}$ | CONTRL | PIDSET <br> SW VAL LSP'S RSPSRC* SP TRK PWR UP PWROUT SP Hi SP Lo ACTION OUT Hi OUT Lo D BAND HYST FAILSF FSMODE PBorGN MINRPM |  | ONE <br> 0.00 <br> ONE <br> NONE* <br> NONE <br> AMLS <br> LAST <br> 2400 <br> 0 <br> REV <br> 100 <br> 0 <br> 2.0 <br> 0.5 <br> 0.0 <br> NOL <br> PB <br> RPM |
|  | SPRATE <br> EUHRUP <br> EUHRDN <br> SPPROG <br> PVSTRT* |  | DIS <br> 0 <br> 0 <br> DIS <br> ENAB* | OPTION | AUXOUT 0 PCT 100 PCT CRANGE DIG IN 1 <br> DI1 CMB <br> DIG IN 2 <br> DI2 CMB |  | OUT <br> 0 <br> 100 <br> 4-20 <br> NONE <br> DIS |
| ATUNE | FUZZY <br> TUNE DUPLEX AT ERR |  | DIS TUNE MAN --- |  |  |  | NONE DIS |
|  |  |  |  | COM <br> Not Installed <br> Infrared Interface on ETC25A | ComADR <br> ComSTA <br> IRENAB* BAUD <br> TX DLY <br> WS_FLT SDENAB SHDTIM SDMODE SHD_SP UNITS CSRATO CSP_BI LOOPBK |  | $\stackrel{3}{\text { DIS }}$ <br> ENAB* <br> 19.2K <br> FP_B <br> Enable <br> ${ }^{0}$ Last <br> LSP <br> PCT <br> 1.0 <br> DIS |
| ALGOR | CTRALG TIMER PERIOD START L DISP RESET INCRMT |  | PIDA DIS <br> 0:01 <br> KEY <br> TREM KEY <br> MIN |  |  |  |  |
| OUTALG | OUTALG CRANGE* RLY TYP MTRTI |  | $\begin{aligned} & \text { RLY / CUR* } \\ & 4-20^{*} \\ & \text { MECH } \\ & 15 \end{aligned}$ |  |  |  |  |
|  |  |  |  | ALARMS | A1S1TY <br> A1S1VA <br> A1S1HL <br> A1S1EV <br> A1S2TY <br> A1S2VA <br> A1S2HL <br> A1S2EV <br> A2S1TY <br> A2S1VA <br> A2S1HL <br> A2S1EV <br> A2S2TY <br> A2S2VA <br> A2S2HL <br> A2S2EV <br> ALHYST <br> ALARM1 <br> BLOCK <br> DIA AL |  | NONE <br> 90 <br> HIGH <br> BEGN |
| INPUT1 | IN1TYP <br> XMITR1 <br> IN1 HI <br> IN1 LO <br> RATIO1 <br> BIAS 1 <br> FILTR1 <br> BRNOUT <br> EMIS |  | $\begin{aligned} & \text { KH } \\ & \text { LIN } \\ & 2400 \\ & 0 \\ & 1.00 \\ & 0.0 \\ & 1.0 \\ & \text { UP } \\ & 1.0 \end{aligned}$ |  |  |  | NONE <br> 10 <br> HIGH <br> BEGN <br> NONE <br> 95 <br> HIGH <br> BEGN <br> NONE <br> 5 |
| INPUT2 <br> ETC25A only | IN2TYP <br> LIN <br> IN2 HI <br> IN2 LO <br> RATIO2 <br> BIAS 2 <br> FILTR2 |  | $1-5 \mathrm{~V}^{*}$LIN$2400^{*}$$0^{*}$$1.00^{*}$$0.0^{*}$$1.0^{*}$ |  |  |  | HIGH <br> BEGN <br> 0.1 <br> NOL <br> DIS <br> DIS |
|  |  |  |  | DISPLY | DECMAL UNITS FREQ NOLDSP DISPLY LNGUAG |  | NONE <br> F <br> 60 <br> DIS <br> SP <br> ENGL |

## Step 6. Start Up Procedure for Operation

Table 6-1: ETL25 Limit

| Step | Operation | Press | Result |
| :---: | :---: | :---: | :--- |
| $\mathbf{1}$ | Display Setpoint | Lower <br> Display | Press the "Lower Display" key till SP appears. |
| $\mathbf{2}$ | Enter the Limit <br> Setpoint | Sor | Set the SP, using the Up \& Down arrow keys, to the desired Limit Setpoint |
| $\mathbf{3}$ | Store the Limit <br> Setpoint | Lower <br> Display | Press the "Lower Display" to store the value. |
| $\mathbf{4}$ | If the display flashes <br> "Limit" | Me-A | Press the Auto-Man/ Reset key. <br> For high limit, the temperature must be under the setpoint before it will reset. |

Table 6-2: ETC25 \& ETC25A

| Step | Operation | Press | Result |  |
| :---: | :---: | :---: | :--- | :--- |
| $\mathbf{1}$ | Select Manual Mode | Adjust the Output | Un-A | Until "M" indicator is ON. <br> The controller is in manual mode. |
| $\mathbf{2}$ | Reset |  |  |  |

## Supplemental Instructions for PV Hot Start for Setpoint Ramp and Setpoint Program (ETC25A)

When power is lost and resumed, the Setpoint Ramp or Setpoint Program will be placed in "HOLD". Using the RUN/HOLD key or a switch on the digital input, you can then remotely restart the ramp or program either at the current PV (PV Hot Start Enabled) or at the original starting setpoint of the SP Ramp or SP Program.
PV STRT can be configured to ENAB or DIS under the SP RAMP or SP PROGRAM Set Up groups. The rules for PV Hot Start (initializing the setpoint at the current PV on power up) are:

- Occurs only if PV Start is ENABLED in either SP RAMP or SP PROGRAM groups
- Occurs only following a power up
- Occurs only for Local Setpoint \#1, and does not apply for Local Setpoint \#2 or Remote Setpoint
- Applies in either Auto or Manual mode
- Following PV Hot Start, Local Setpoint \#1 and Local Setpoint \#2 can be changed via the increment/decrement keys

The Digital Input can be configured to RUN or STRT.
RUN - the program starts the setpoint at the current value of setpoint \#1; reopening the contact returns to the HOLD state. If PV STRT is enabled, the value of setpoint \#1 will be the value of the process variable PV following a power up.
STRT - the program starts the setpoint at the original value that was selected when the SP RAMP or SP PROGRAM was first started; reopening the contact has no effect.

- This action occurs either after a power cycling or after the SP PROGRAM has completed and the STATE at program end is configured for HOLD.
- The Digital Input must be selected for STRT before the SP RAMP or SP PROGRAM is put into RUN via the RUN/HOLD key in order to capture and save the original starting setpoint value.
- If the SP RAMP or SP PROGRAM is in the RUN state and then put in the HOLD state, contact closure will re-start the program at the setpoint value existing at the time when it was put into the HOLD state.
- Once in the RUN state, then this contact closure will have no effect.
- If this contact is held closed through the time that power cycles off and on, the action will occur in accordance with the rules above.


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